

Lecture 8.

As previously advertised, the advantage of the notion of  $\psi$ -convexity is that it can be checked locally near each boundary point. This is a consequence of:

Thm 3. Let  $\Omega \subseteq \mathbb{C}^n$ . TFAE:

- (i)  $\Omega$  is  $\psi$ -convex, i.e.  $-\log d(z, \Omega^c)$  is PSH( $\Omega$ ).
- (ii)  $u(z) = -\log d(z, \Omega^c)$  is PSH near the boundary, i.e.,  $\exists$  closed  $F \subseteq \Omega$  s.t.  $u \in \text{PSH}(\Omega \setminus F)$ .
- (iii)  $\exists$  cont., PSH exhaustion function  $v$ , i.e.,  $\{z: v(z) < c\} \subset \subset \Omega$  for all  $c \in \mathbb{R}$ .

The implications (i)  $\Rightarrow$  (ii)  $\Rightarrow$  (iii) are easy. The implication (iii)  $\Rightarrow$  (i) goes via an additional (iv) similar to the characterization of DohT by holomorphic hulls of compacts. Details are in Hörmander, Sec. 2.6.

Using (ii), one easily sees:

Cor 1.  $\Omega \subseteq \mathbb{C}^n$  is  $\psi$ -convex  $\Leftrightarrow \forall p \in \partial\Omega \exists$  open nbhd  $U_p$  of  $p$  s.t.  $\Omega \cap U_p$  is  $\psi$ -convex.

# The Levi form and convexity

Let us now assume that  $M = \partial\Omega \subseteq \mathbb{C}^n$  is a  $C^2$ -smooth  $(2n-1)$ -dim  $(\mathbb{R})$  mfd.

Let  $\rho = 0$  be a defining function

for  $M$ , i.e.  $\rho: \mathbb{C}^n \rightarrow \mathbb{R}$  is  $C^2$ ,  $d\rho \neq 0$  on  $M$ , and  $M = \{z: \rho(z, \bar{z}) = 0\}$

Note. Any two defining functions  $\rho, \tilde{\rho}$  are related by  $\rho = a\tilde{\rho}$ , where  $a \in C^2$  and  $a \neq 0$  on  $M$ .

A convenient notion to remind you that when taking derivatives you need both

$$\frac{\partial \rho}{\partial z_n}, \frac{\partial \rho}{\partial \bar{z}_2} \text{ etc.},$$

to capture all real derivatives

$$\frac{\partial \rho}{\partial x_n}, \frac{\partial \rho}{\partial y_2}.$$

Def. For  $p \in M$ ,  $\underline{T}_p^{1,0} M \subseteq \underline{T}_p^{1,0} \mathbb{C}^n$  consists

of  $\xi = \sum_{j=1}^n \xi_j \frac{\partial}{\partial z_j} \in \underline{T}_p^{1,0} \mathbb{C}^n$  s.t.

$$\sum_{j=1}^n \frac{\partial \rho}{\partial z_j}(p) \xi_j = 0.$$

It follows easily from the Note above that  $T_p M$  is independent of choice of  $\rho$ .

Moreover, since  $\partial\rho = \sum_{j=1}^n \frac{\partial\rho}{\partial z_j} dz_j$  does not vanish on  $M$ ,  $T_p M$  is a  $(n-1)$ -dim  $\mathbb{C}$  subspace of  $T_p \mathbb{C}^n \cong \mathbb{C}^n$ .

Thm 1 Let  $\Omega \subseteq \mathbb{C}^n$  and assume  $M = \partial\Omega$  is  $\mathbb{C}^2$  w/a defining function  $\rho$  s.t.  $\Omega = \{\rho < 0\}$ .

Then,  $\Omega$  is  $\psi$ CVX  $\Leftrightarrow \forall \xi \in T_p \partial\Omega$

$$(*) \quad \sum_{i,j=1}^n \frac{\partial^2 \rho}{\partial z_i \partial \bar{z}_j} (p) \xi_i \bar{\xi}_j \geq 0, \quad \forall \xi \in T_p \partial\Omega$$

Pf. We note that (\*) is independent of the choice of defining function. If  $\tilde{\rho} = a\rho$  is another (with  $a > 0$ ), then

$$\frac{\partial \tilde{\rho}}{\partial z_i} = a \frac{\partial \rho}{\partial z_i} + \rho \frac{\partial a}{\partial z_i}, \quad \frac{\partial^2 \tilde{\rho}}{\partial z_i \partial \bar{z}_j} = a \frac{\partial^2 \rho}{\partial z_i \partial \bar{z}_j}$$

$$+ \frac{\partial \rho}{\partial z_i} \frac{\partial a}{\partial \bar{z}_j} + \frac{\partial \rho}{\partial \bar{z}_j} \frac{\partial a}{\partial z_i} + \rho \frac{\partial^2 a}{\partial z_i \partial \bar{z}_j}.$$

Thus, if  $p \in M$  ( $\Rightarrow \rho(p) = 0$ ) and  $\xi \in T_p M$  ( $\Rightarrow \sum_{i=1}^n \frac{\partial \rho}{\partial z_i} \xi_i = \sum_{j=1}^n \frac{\partial \rho}{\partial \bar{z}_j} \bar{\xi}_j = 0$ ), we find